

KNOWLEDGEBASE DOCUMENT

UNIM068

Subject: Commissioning of Leroy Somer Interchangeable Dyneo⁺ Motor (Without Position Feedback) with Unidrive M700 / M701 / M702

Documentation Category: Drive setup, gain settings, autotune

Product Category: Unidrive M

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Circulation: End Users

Revision History

Revision	Date	Revising Author	Comments
1.00	23/10/2020	Mike Quinlan	Initial Version
2.00	04/02/2022	Mike Quinlan	

Summary of Contents

This document details the set-up of Leroy Somer Dyneo⁺ motors (11 to 90kW interchangeable version, 1500/3000rpm) without position feedback on Unidrive M700/701/702.

1. Introduction

Before setting the drive, please follow the safety and installation instructions for Dyneo⁺ motors and Unidrive M700/701/702 drives described in their respective manuals.

Dyneo⁺ motors: http://www.leroy-somer.com/documentation_pdf/5411_en.pdf

Unidrive M700/701/702 drives: see the Getting started guide and associated Power Installation Guides (available from the Control Techniques website).



The installation and commissioning must be carried out by qualified, competent and authorized personnel.

Then proceed with the quick commissioning described in §2 from the factory setting.

Requirements:

- Parameters shown in motor data tables from the annex are only applicable for the Unidrive M700/701/702 drive rating indicated for each data line. If a drive with a different rating is used, then *Current Controller Kp Gain (Pr 04.013)* and *Current Controller Ki Gain (Pr 04.014)* must be scaled, as detailed below:

$$\text{New value} = \text{Annex value} \times (\text{Kc}_{\text{New drive}} / \text{Kc}_{\text{Annex drive}})$$

Values for Kc can be found in the Parameter Reference Guide, in the Current Ratings section.

- Ensure the drive has a firmware version equal or higher than V01.20.00.00.

2. Commissioning with Unidrive M700/701/702: RFC-S mode for interchangeable Dyneo⁺ permanent magnet motors without position feedback (sensorless)

Action	Description																																																																																																																																																						
Before power-up	<p>Ensure:</p> <ul style="list-style-type: none"> The drive enable signal is not given (terminal 31 on Unidrive M700 / M701 and terminals 11 & 13 on Unidrive M702). The Run signal is not given Motor is connected 																																																																																																																																																						
Power-up the drive	<p>If RFC-S mode is displayed when the drive is powered up:</p> <ul style="list-style-type: none"> If the frequency of the mains supply is 60Hz, set Pr 00.000 = 1244, otherwise if the frequency of the mains is 50Hz, set Pr 00.000 = 1233. <p>If Open Loop or RFC-A mode is displayed when the drive is powered up:</p> <ul style="list-style-type: none"> Set Pr 00.048 = RFC-S (3). If the frequency of the mains supply is 60Hz, set Pr 00.000 = 1254, otherwise if the frequency of the mains is 50Hz, Pr 00.000 = 1253. <p>Press the red Reset button or toggle the Reset logic input.</p> <p>These actions will leave the drive in RFC-S mode with defaulted parameters. The drive will be in a tripped state, but the associated trips are addressed by settings within this procedure.</p>																																																																																																																																																						
Advanced menu access from the keypad	<p>To access all menus required for commissioning, set Pr 00.049 = All Menus (1). Reminder: Select the menus using the left and right arrows. The parameters are selected using the up and down arrows.</p>																																																																																																																																																						
Motor thermistor set-up	<p>The motor PTC thermistor must be connected to the drive:</p> <ul style="list-style-type: none"> M700/M701: Connect thermistor to analogue input 3 (terminals 8 and 11). M702 (with date code 1710 or later): Connect thermistor to digital input 5 / analogue input 3 (terminals 8 and 10). <p>For the drive to manage the thermistor, set Analogue Input 3 Mode Pr 07.015 = Therm Short Cct (7). If connection of the thermistor leaves insufficient inputs, then it may be necessary to fit an SI-I/O module.</p>																																																																																																																																																						
Enter motor nameplate details	<p>Refer to the Dyneo+ motor tables located in the Appendix.</p> <p>Select the table corresponding to the motor speed range (1500 or 3000 rpm). Then depending on the motor type and its power, select the line that corresponds to the voltage, the supply frequency and the rated speed of the application. From this line, set in the drive the values of all the parameters listed in the table.</p> <p>NOTE: If the motor type does not appear in the table, then it is from the Compact range. In this case, please contact Control Techniques Technical Support.</p> <p>Example: For the 1500 range motor, LSHRM 160MR1 – 11 kW 400V – 50Hz with a rated speed of 1500 rpm, parameter values to set in the drive are the ones of the green line as indicated below:</p> <table border="1"> <thead> <tr> <th rowspan="3">1500 range Motor Type</th> <th rowspan="3">Powerdrive F300 Drive type</th> <th colspan="18">Parameters</th> </tr> <tr> <th>04.013</th> <th>04.014</th> <th>05.007</th> <th>05.008</th> <th>05.009</th> <th>05.011</th> <th>05.017</th> <th>05.024</th> <th>05.033</th> <th>05.069</th> <th>05.072</th> <th>05.075</th> <th>05.078</th> <th>05.082</th> <th>05.084</th> <th>05.087</th> </tr> <tr> <th>Motor Rated Frequency</th> <th>Current controller Kp/Gain</th> <th>Current controller KI Gain</th> <th>Rated current</th> <th>Rated speed</th> <th>Rated voltage</th> <th>Number Of Motor Poles</th> <th>Stator Resistance</th> <th>Ld</th> <th>Volts per 1000 rpm</th> <th>Over-current Trip Level</th> <th>No-load Lq</th> <th>Iq Test Current For Inductance Measurement</th> <th>Lq At The Defined Iq Test Current</th> <th>Id Test Current For Inductance Measurement</th> <th>Lq At The Defined Id Test Current</th> <th>User Defined Rated Torque Angle</th> </tr> <tr> <th>Hz</th> <th>-</th> <th>-</th> <th>A</th> <th>rpm</th> <th>V</th> <th>Ω</th> <th>mH</th> <th>V/kmin-1</th> <th>% Inom</th> <th>mH</th> <th>%</th> <th>mH</th> <th>%</th> <th>mH</th> <th>%</th> <th>°</th> </tr> </thead> <tbody> <tr> <td colspan="2">LSHRM 160 MR1_11 kW</td><td>044-00240A</td><td>50</td><td>152</td><td>269</td><td>21</td><td>1500</td><td>400</td><td>4 Poles</td><td>0.315822</td><td>7.63</td><td>72</td><td>236%</td><td>68.5</td><td>73</td><td>44.8</td><td>-108</td><td>68.5</td><td>56</td></tr> <tr> <td colspan="2"></td><td>044-00240A</td><td>60</td><td>152</td><td>269</td><td>20</td><td>1800</td><td>400</td><td>4 Poles</td><td>0.315822</td><td>7.63</td><td>72</td><td>244%</td><td>68.5</td><td>73</td><td>44.8</td><td>-108</td><td>68.5</td><td>56</td></tr> <tr> <td colspan="2"></td><td>044-00240A</td><td>60</td><td>152</td><td>269</td><td>21</td><td>1800</td><td>400</td><td>4 Poles</td><td>0.315822</td><td>7.63</td><td>72</td><td>233%</td><td>68.5</td><td>73</td><td>44.8</td><td>-108</td><td>68.5</td><td>56</td></tr> <tr> <td colspan="2"></td><td>064-00480A</td><td>87</td><td>124</td><td>219</td><td>38</td><td>2600</td><td>400</td><td>4 Poles</td><td>0.105274</td><td>2.54</td><td>42</td><td>218%</td><td>22.8</td><td>73</td><td>14.9</td><td>-108</td><td>22.8</td><td>56</td></tr> </tbody> </table> <p>NOTE: When setting Pr 05.069, it may be necessary to increase the value entered, to ensure that the actual trip level displayed in Pr 05.068 is close to (but not greater than) the required value.</p>	1500 range Motor Type	Powerdrive F300 Drive type	Parameters																		04.013	04.014	05.007	05.008	05.009	05.011	05.017	05.024	05.033	05.069	05.072	05.075	05.078	05.082	05.084	05.087	Motor Rated Frequency	Current controller Kp/Gain	Current controller KI Gain	Rated current	Rated speed	Rated voltage	Number Of Motor Poles	Stator Resistance	Ld	Volts per 1000 rpm	Over-current Trip Level	No-load Lq	Iq Test Current For Inductance Measurement	Lq At The Defined Iq Test Current	Id Test Current For Inductance Measurement	Lq At The Defined Id Test Current	User Defined Rated Torque Angle	Hz	-	-	A	rpm	V	Ω	mH	V/kmin-1	% Inom	mH	%	mH	%	mH	%	°	LSHRM 160 MR1_11 kW		044-00240A	50	152	269	21	1500	400	4 Poles	0.315822	7.63	72	236%	68.5	73	44.8	-108	68.5	56			044-00240A	60	152	269	20	1800	400	4 Poles	0.315822	7.63	72	244%	68.5	73	44.8	-108	68.5	56			044-00240A	60	152	269	21	1800	400	4 Poles	0.315822	7.63	72	233%	68.5	73	44.8	-108	68.5	56			064-00480A	87	124	219	38	2600	400	4 Poles	0.105274	2.54	42	218%	22.8	73	14.9	-108	22.8	56
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Set maximum speed	Set the maximum speed in Pr 01.006 .																																																																																																																																																						
Set acceleration and deceleration rates	<p>Set:</p> <ul style="list-style-type: none"> Ramp Rate Units (Pr 02.039) = On (1) Acceleration rate in Pr 02.011 (s up to Pr 01.006) - A value of 20s suits most applications. Deceleration rate in Pr 02.021 (s up to Pr 01.006) - A value of 20s suits most applications. <p>If a braking resistor is installed, set Pr 02.004 = Fast (0). Also ensure Pr 10.030 and Pr 10.031 and Pr 10.061 are set correctly, otherwise premature 'Brake R Too Hot' trips may be seen.</p>																																																																																																																																																						

Additional settings	<p>Set:</p> <ul style="list-style-type: none"> • Speed Controller Proportional Gain K_p (Pr 03.010) = 0.0300 • Speed Controller Integral Gain K_i (Pr 03.011) = 0.10 • RFC Feedback Mode (Pr 03.024) = Sensorless • P1 Error Detection Level (Pr 03.040) = 0 • P1 Thermistor Fault Detection (Pr 03.123) = None • Motoring Current Limit (Pr 04.005) = 120% max • Regenerating Current Limit (Pr 04.006) = 120% max • Symmetrical Current Limit (Pr 04.007) = 120% max • Current Reference Filter 1 Time Constant (Pr 04.012) = 1ms [It may be necessary to increase this value to counteract ripple from low resolution estimated feedback] • Thermal Protection Mode (Pr 04.016) = Disabled • User Current Maximum Scaling (Pr 04.024) = 120% max • Maximum Switching Frequency (Pr 05.018) = 3kHz • Enable High Speed Mode (Pr 05.022) = Enable (2) • Flux Control Gain (Pr 05.027) = 0.1 • Minimum Switching Frequency (Pr 05.038) = 3kHz (1) • Voltage Headroom (Pr 05.041) = 5% [Do not set a lower value. Increase this value to 10%, if the motor is unstable in the field weakening area] • RFC Low Speed Mode (Pr 05.064) = Injection • Saliency Torque Control Select (Pr 05.065) = Auto [Ensure that Pr 05.066 = High, otherwise check the value entered for Pr 05.087 from the table] • Inverted Saturation Characteristic (Pr 05.070) = On (1) • Low Speed Sensorless Mode Current (Pr 05.071) = 60% [Note: This forces a reduced current limit between zero speed and 20% of motor rated speed] • Stop Mode (Pr 06.001) = Ramp • Hold Zero Speed (Pr 06.008) = 0 (Disabled) <p>If the load is a high inertia, Pr 03.010 may need to be increased.</p>
Save parameters	Select 'Save Parameters' in Pr mm.000 and press the red reset button or toggle the reset digital input.

3000 range Motor Type	Powerdrive F300 Drive Type	Parameters																
		05.006	04.013	04.014	05.007	05.008	05.009	05.011	05.017	05.024	05.033	05.069	05.072	05.075	05.078	05.082	05.084	05.087
		Motor Rated Frequency	Current controller Kp Gain	Current controller Ki Gain	Rated current	Rated speed	Rated voltage	Number Of Motor Poles	Stator Resistance	Transient Inductance / Ld	Volts per 1000 rpm	Over- current Trip Level	No-load Lq	Iq Test Current For Inductance Measurement	Lq At The Defined Iq Test Measurement	Id Test Current for Inductance Measurement	Lq At The Defined Id Test Current	User Defined Rated Torque Angle
Hz	-	-	A	rpm	V		Ω	mH	V/kmin-1	% Inom	mH	%	mH	%	mH	%	mH	°
LSHRM 160 MR1_11kW	044-00240A	100	95	213	20	3000	400	4 Poles	0.250147	4.78	43	238%	41.3	73	27.8	-108	41.3	56
	044-00240A	120	95	213	20	3600	400	4 Poles	0.250147	4.78	43	244%	41.3	73	27.8	-108	41.3	56
	044-00240A	120	95	213	20	3600	460	4 Poles	0.250147	4.78	43	243%	41.3	73	27.8	-108	41.3	56
	064-00480A	173	78	173	36	5200	400	4 Poles	0.083382	1.59	25	223%	13.8	73	9.3	-108	13.8	56
LSHRM 160 MR1_15kW	064-00380A	100	117	223	28	3000	400	4 Poles	0.128766	2.88	39	254%	25.5	75	17.7	-106	25.5	55
	054-00300A	120	90	172	27	3600	400	4 Poles	0.128766	2.88	39	259%	25.5	75	17.7	-106	25.5	55
	064-00380A	120	117	223	28	3600	460	4 Poles	0.128766	2.88	39	249%	25.5	75	17.7	-106	25.5	55
	064-00630A	173	52	100	51	5200	400	4 Poles	0.042922	0.96	23	226%	8.5	75	5.9	-106	8.5	55
LSHRM 160 LR1_18,5kW	064-00380A	100	117	223	34	3000	400	4 Poles	0.128766	2.88	39	209%	25.5	71	16.0	-109	25.5	57
	064-00380A	120	117	223	33	3600	400	4 Poles	0.128766	2.88	39	214%	25.5	71	16.0	-109	25.5	57
	064-00380A	120	117	223	33	3600	460	4 Poles	0.128766	2.88	39	212%	25.5	71	16.0	-109	25.5	57
	074-00790A	173	74	140	62	5200	400	4 Poles	0.042922	0.96	23	186%	8.5	71	5.3	-109	8.5	57
LSHRM 180 M1_22kW	064-00480A	100	104	192	42	3000	400	4 Poles	0.092501	2.13	38	216%	15.8	76	12.6	-105	15.8	54
	064-00480A	120	104	192	40	3600	400	4 Poles	0.092501	2.13	38	224%	15.8	76	12.6	-105	15.8	54
	064-00480A	120	104	192	41	3600	460	4 Poles	0.092501	2.13	38	218%	15.8	76	12.6	-105	15.8	54
	074-00940A	173	64	118	74	5200	400	4 Poles	0.030834	0.71	22	200%	5.3	76	4.2	-105	5.3	54
LSHRM 200 LQ1_30kW	064-00630A	100	116	215	57	3000	400	4 Poles	0.092501	2.13	38	159%	15.8	69	11.0	-110	15.8	58
	064-00630A	120	116	215	57	3600	400	4 Poles	0.092501	2.13	38	158%	15.8	69	11.0	-110	15.8	58
	064-00630A	120	116	215	57	3600	460	4 Poles	0.092501	2.13	38	160%	15.79	69	11.0	-110	15.8	58
LSHRM 200 LQ1_37kW	074-00790A	100	109	174	70	3000	400	4 Poles	0.053326	1.42	37	178%	10.8	71	8.0	-109	10.8	57
	074-00790A	120	109	174	69	3600	400	4 Poles	0.053326	1.42	37	181%	10.8	71	8.0	-109	10.8	57
	074-00790A	120	109	174	69	3600	460	4 Poles	0.053326	1.42	37	181%	10.8	71	8.0	-109	10.8	57
LSHRM 225 MY1_45kW	074-00940A	100	106	142	84	3000	400	4 Poles	0.037145	1.185	38	180%	9.2	71	6.8	-109	9.2	57
	074-00940A	120	106	142	82	3600	400	4 Poles	0.037145	1.185	38	184%	9.2	71	6.8	-109	9.2	57
	074-00940A	120	106	142	83	3600	460	4 Poles	0.037145	1.185	38	181%	9.2	71	6.8	-109	9.2	57
LSHRM 250 ME_55 kW	074-01120A	100	118	104	100	3000	400	4 Poles	0.021063	1.019	43	226%	9.5	71	5.7	-109	9.5	57
	074-01120A	120	118	104	101	3600	400	4 Poles	0.021063	1.019	43	225%	9.5	71	5.7	-109	9.5	57
	074-01120A	120	118	104	100	3600	460	4 Poles	0.021063	1.019	43	226%	9.5	71	5.7	-109	9.5	57
LSHRM 280 SC_75 kW	084-01550A	100	123	109	138	3000	400	4 Poles	0.016370	0.794	38	185%	7.4	65	4.1	-113	7.4	60
	084-01550A	120	123	109	136	3600	400	4 Poles	0.016370	0.794	38	187%	7.4	65	4.1	-113	7.4	60
	084-01550A	120	123	109	135	3600	460	4 Poles	0.016370	0.794	38	189%	7.4	65	4.1	-113	7.4	60
LSHRM 280 MC_90 kW	084-01840A	100	112	88	167	3000	400	4 Poles	0.011253	0.617	38	190%	5.9	65	3.3	-113	5.9	60
	084-01840A	120	112	88	160	3600	400	4 Poles	0.011253	0.617	38	198%	5.9	65	3.3	-113	5.9	60
	084-01840A	120	112	88	168	3600	460	4 Poles	0.011253	0.617	38	189%	5.9	65	3.3	-113	5.9	60